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END OF SEARCH HISTORY

Key: **IEEE JNL** = IEEE Journal or Magazine, **IEE JNL** = IEE Journal or Magazine, **IEEE CNF** = IEEE Conference, **IEE CNF** = IEE Conference, **IEEE STD** = IEEE Standard

- 1. Creating spatial temporal database by autonomous mobile surveillance system (a study of mobile robot surveillance system using spatial temporal GIS part 1)**
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6-9 June 2005 Page(s):143 - 150
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- 2. Distributed surveillance and reconnaissance using multiple autonomous ATVs: CyberScout**
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- 3. Urban Object Recognition from Informative Local Features**
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- 4. Visual sign information extraction and identification by deformable models for intelligent vehicles**
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- 5. Onboard real-time system for 3D urban environment reconstruction**
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- 6. Development of an Autonomous Mobile Surveillance System Using a Network-based RTK-GPS**
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8. 4-D/RCS: a reference model architecture for Demo III

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9. A voting-based approach for fast object recognition in underwater acoustic images

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10. Brightness-independent start-up routine for star trackers

Accardo, D.; Rufino, G.;

Aerospace and Electronic Systems, IEEE Transactions on
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11. Star recognition algorithm for APS star tracker: oriented triangles

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12. Using Laser and Vision to Locate a Robot in an Industrial Environment: A Practical Experience

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- 20. Parking-vehicles recognition using spatial temporal data (a study of mobile robot surveillance system using spatial temporal GIS part 2)**
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- 24. Autonomous cross-country navigation: an integrated perception and planning system**
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- 25. Computer vision: an overview**
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